



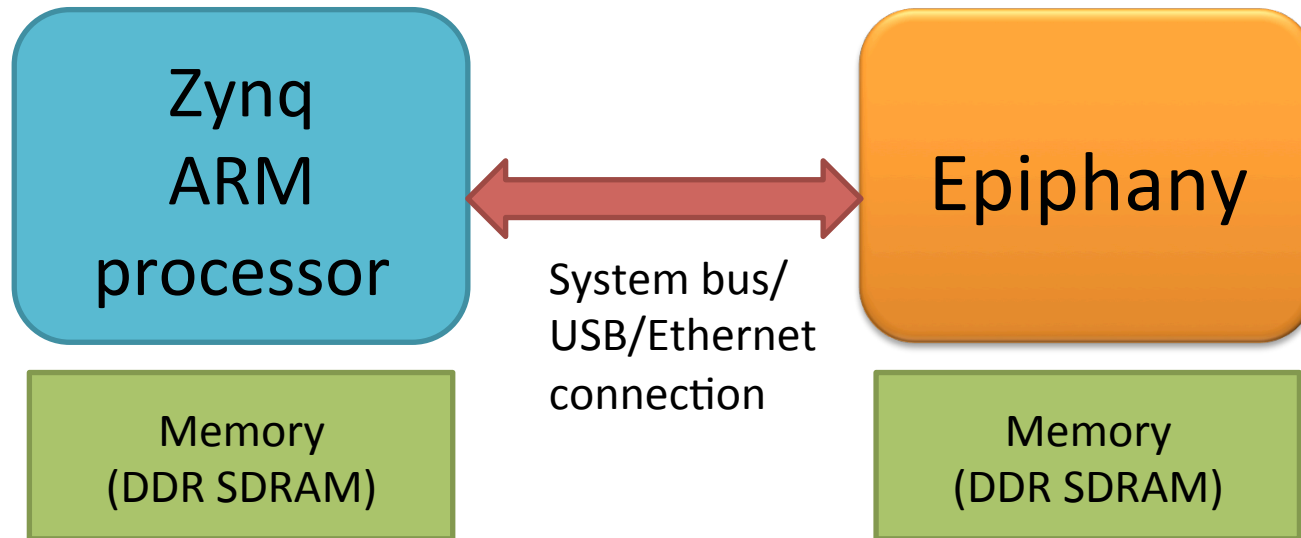
Introduction to Massively Parallel Programming on Epiphany

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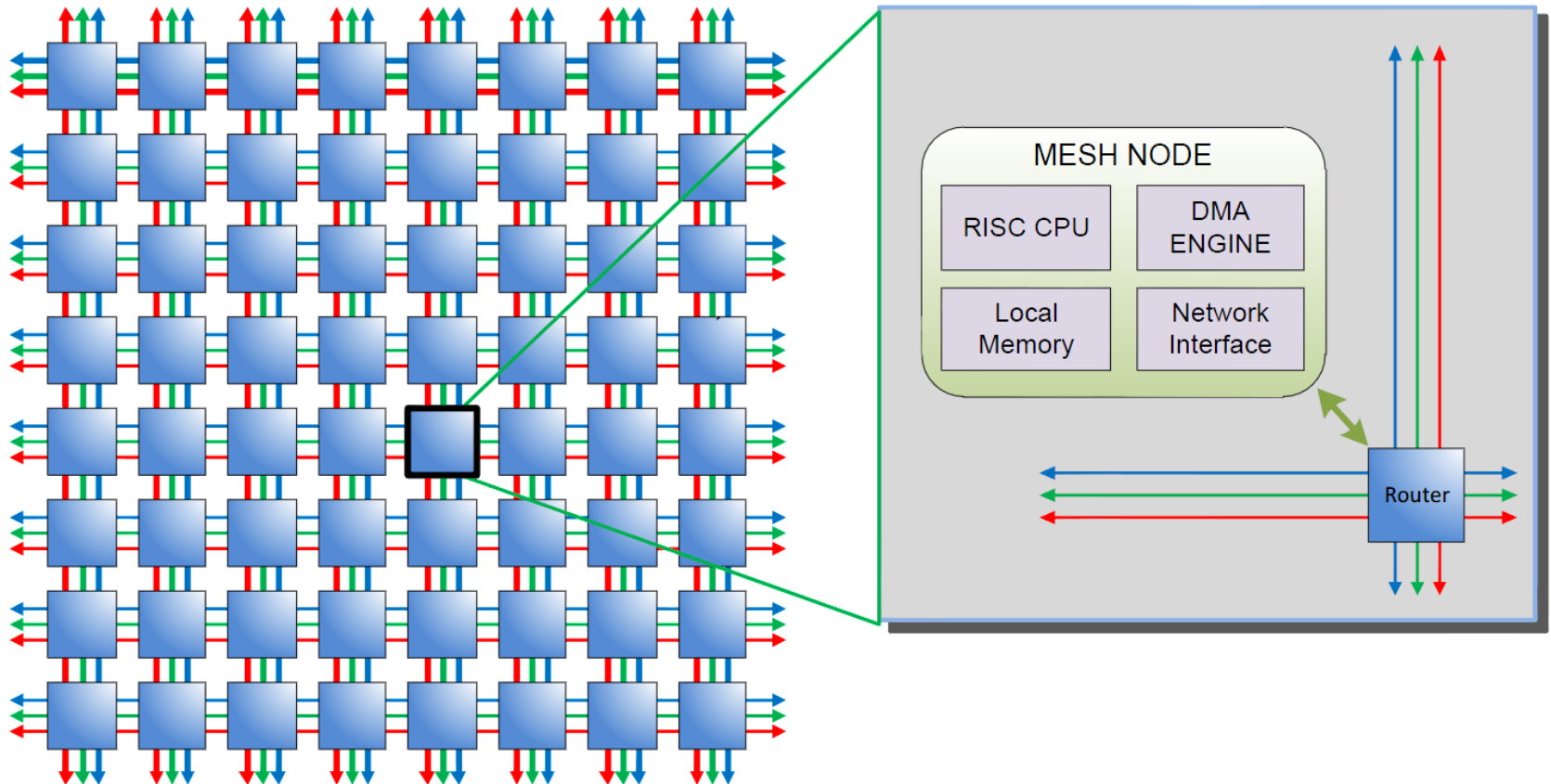
Where is Epiphany on Parallella?



Host processor controls Epiphany by:

- (1) Initializing the system
- (2) Downloading program
- (3) Initializing memory
- (4) Writing the input data
- (5) Reading the results
- (6) Finalizing the system

Inside of Epiphany

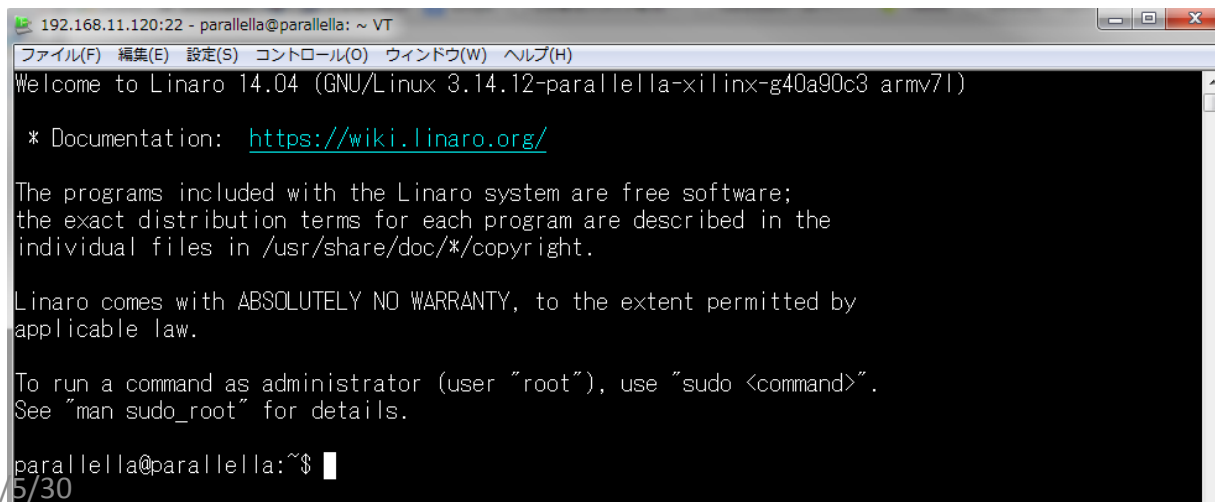


Processors are distributed on each cross points of 2D mesh topology.
(Current release supports 4x4 or 8x8)

How to begin Parallella

- Download the latest Ubuntu kernel and write it to SD card.
`ftp://ftp.parallella.org/ubuntu/dists/trusty/image/`
 - Initially, DHCP is configured.
 - Connect to LAN, and find IP/MAC address in your router. (MAC is 04:4F:XX:XX:XX:XX)
 - Connect terminal such as Teraterm via SSH
 - Login by user: parallella pass: parallella
- Strongly recommend to change password by “passwd” command!

Epiphany SDK is already ready in /opt/adaptiva



The screenshot shows a terminal window titled "192.168.11.120:22 - parallella@parallella: ~ VT". The terminal displays the following text:

```
ファイル(F) 編集(E) 設定(S) コントロール(O) ウィンドウ(W) ヘルプ(H)
Welcome to Linaro 14.04 (GNU/Linux 3.14.12-parallella-xilinx-g40a90c3 armv7l)

* Documentation: https://wiki.linaro.org/

The programs included with the Linaro system are free software;
the exact distribution terms for each program are described in the
individual files in /usr/share/doc/*/copyright.

Linaro comes with ABSOLUTELY NO WARRANTY, to the extent permitted by
applicable law.

To run a command as administrator (user "root"), use "sudo <command>".
See "man sudo_root" for details.

parallella@parallella:~$
```

How to setup Epiphany SDK

- The latest kernel includes Epiphany SDK (ESDK) and Browndeer COPRTHR SDK.
- Currently available programming methods
 - Using Epiphany SDK, Hardwired programming
 - Using COPRTHR SDK, OpenCL

In the future, MPI will be available

The COPRTHR MPI library is not, and will not be, a part of the currently available COPRTHR-1 SDK. Instead it will be available in the future as part of the new COPRTHR-2 software package being developed by BDT.

Hardwired programming by Epiphany SDK

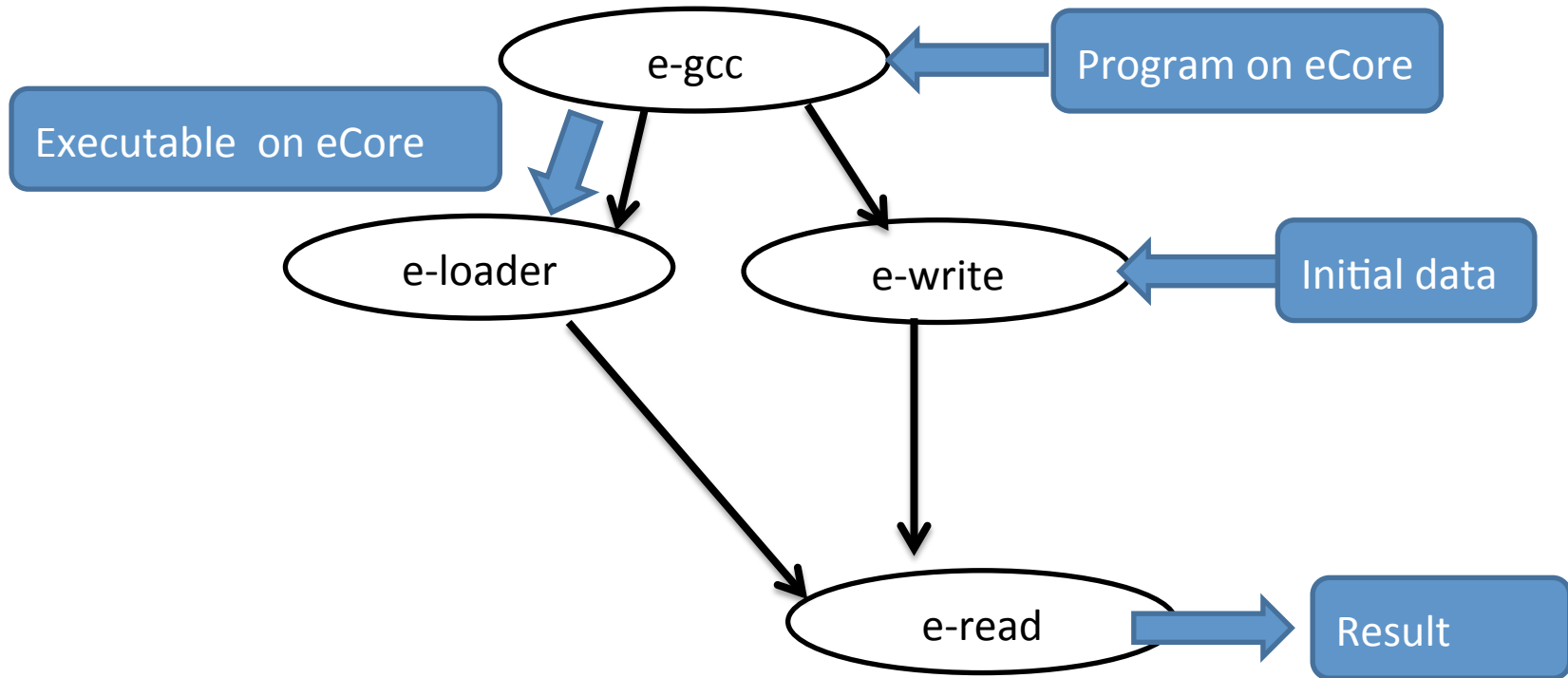
- Programming tools (mainly used)
 - e-gcc : Compiler for Epiphany architecture.
 - e-server : debugger server.
 - e-reset : reset Epiphany
 - e-hw-rev : Checking Epiphany spec.
 - e-loader : loading program into eCore(s)
 - e-read : read memory contents
 - e-write : write memory contents

Dispatch program form commandline.

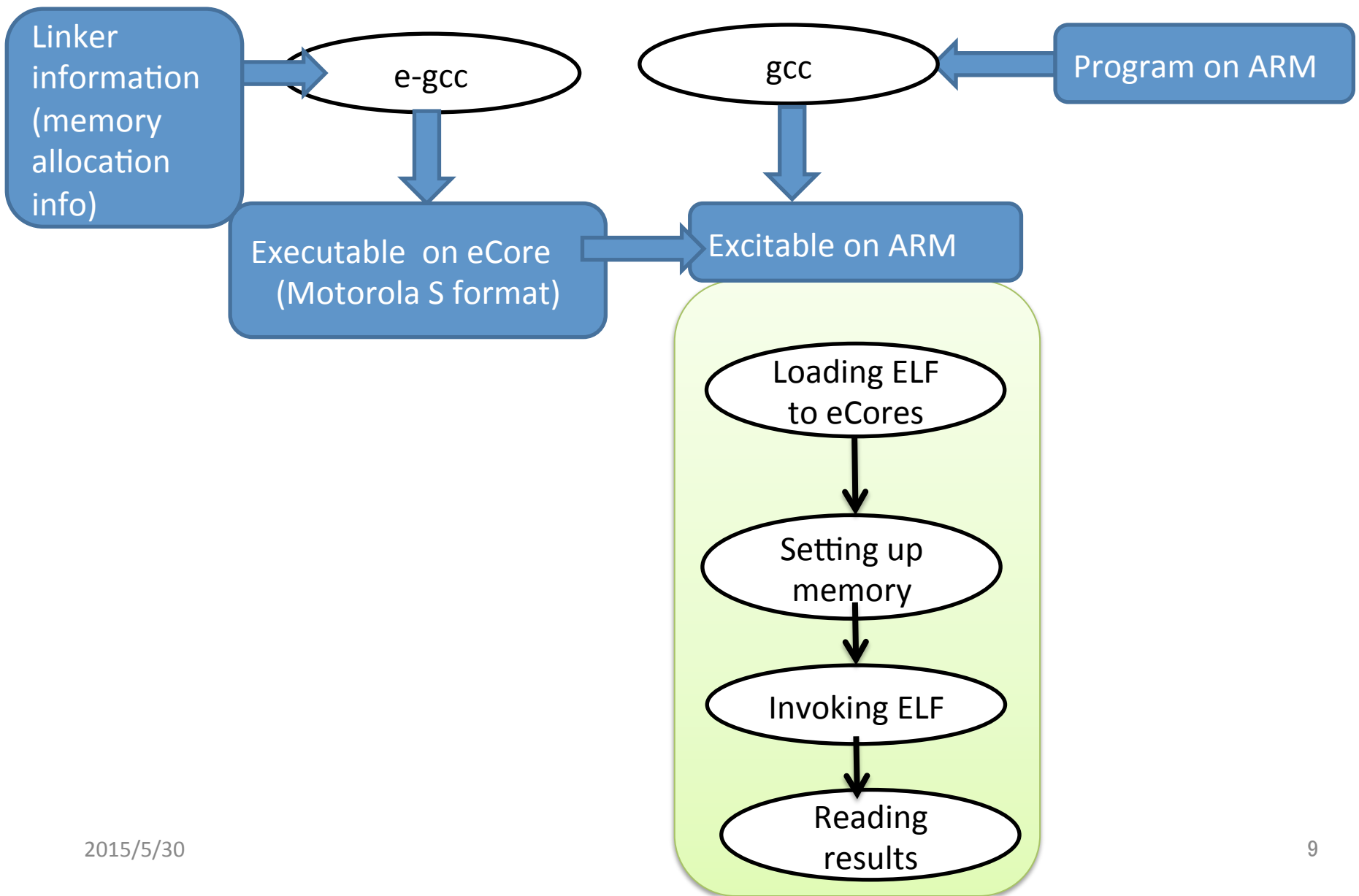
- e-run : invoke downloaded program on eCore
Epiphany simulator is prepared.

DEMONSTRATION ESDK TOOLS

Program invocation from commandline



Program invocation from host program



Library functions for host program

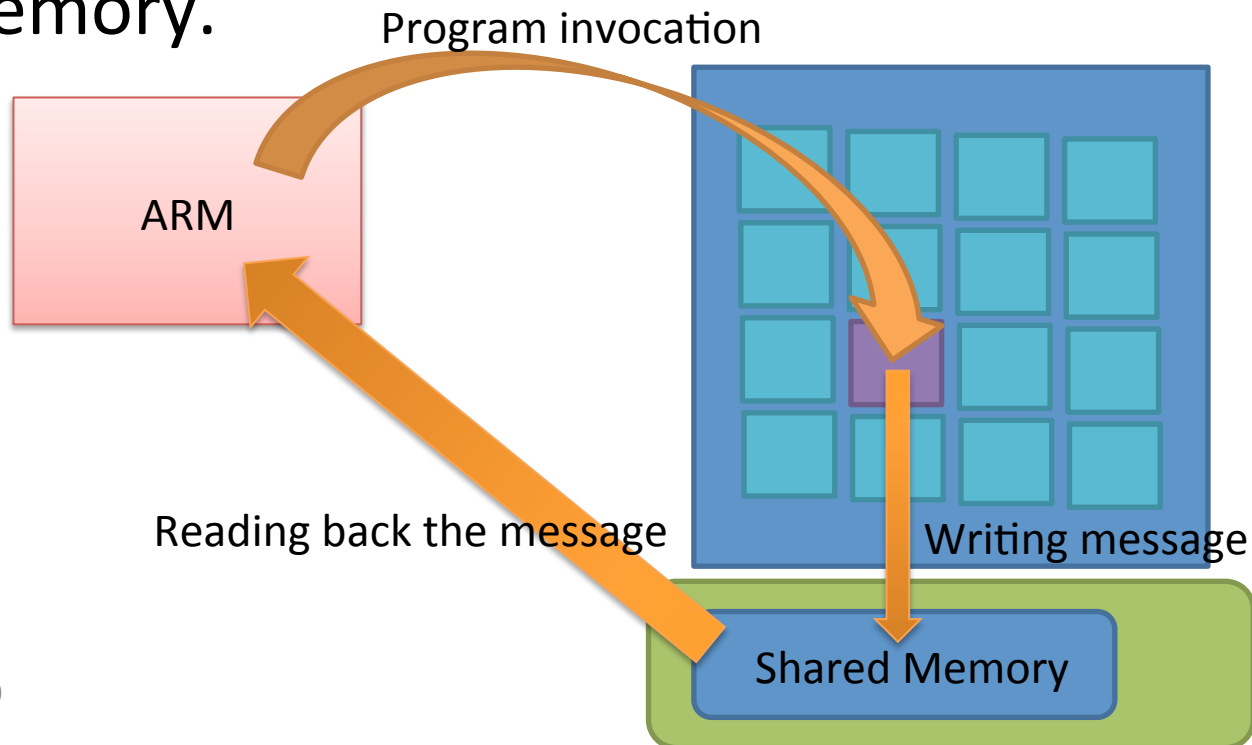
- Include “e_hal.h” and link “libe-hal.a”.
- Main functions:
 - e_init(), e_finalize():
Initializing and finalizing Epiphany system.
 - e_reset_system(): reset Epiphany.
 - e_shm_alloc(), e_shm_release(ShmName):
shared memory allocation and release by name
 - e_shm_attach():
acquire the shared memory searched by the name
 - e_open(), e_close():
open and close the Epiphany processor interface
 - e_load(): load the Epiphany program to core(s)
 - e_read(), e_write(): read and write the data on the Epiphany memory.

Library functions for Epiphany program

- Include “e_lib.h” and link “libe-lib.a”.
- Main functions:
 - e_get_coreid(): get processor ID.
 - e_coords_from_coreid():
get coordinates of the processor in the group.
 - e_shm_attach():
acquire the shared memory searched by the name
 - e_read(), e_write():
read and write the data on the Epiphany memory.

Hello World example

- ARM executes an Epiphany program.
- The Epiphany program will write some message to a shared memory.
- ARM reads the message from the shared memory.



Program on host (ARM)

```
int main(int argc, char *argv[])
{
    unsigned row, col, coreid, i,j;
    e_init(NULL);
    e_reset_system();
    e_get_platform_info(&platform);

    rc = e_shm_alloc(&mbuf, ShmName, ShmSize);
    if (rc != E_OK)
        rc = e_shm_attach(&mbuf, ShmName);
}
```

Initializing Epiphany

Reset Epiphany

Getting platform information

Shard memory allocation

Acquiring the shared memory
and maps the memory address to the host side.

Program on host (ARM) cont.

```
for (i=0; i<platform.rows; i++)  
    for (j=0; j<platform.cols; j++)  
    {  
        e_open(&dev, 0, 0, platform.rows, platform.cols);  
        if ( E_OK != e_load("hello-world.srec", &dev, row, col, E_TRUE) ) {  
            fprintf(stderr, "Failed to load hello-world.srec\n");  
            return EXIT_FAILURE;  
        }  
  
        usleep(10000);  
        e_read(&mbuf, 0, 0, 0, buf, ShmSize);  
        printf("\n%s\n", buf);  
        e_close(&dev);  
    }
```

Opening Epiphany's work group

Loading program

Waiting for program invocation

Reading back the message from the Epiphany side

Printing out the message

Closing the Epiphany

Program on Epiphany

```
int main(void) {  
    coreid = e_get_coreid();  
    e_coords_from_coreid(coreid, &my_row, &my_col);  
    if ( E_OK != e_shm_attach(&emem, ShmName) ) {  
        return EXIT_FAILURE;  
    }  
  
    snprintf(buf, sizeof(buf), Msg, coreid, my_row, my_col);  
  
    e_write((void*)&emem, buf, my_row, my_col, NULL, strlen(buf) + 1);  
  
    return EXIT_SUCCESS;  
}
```

Getting core ID

Getting the coordinate of the core ID

Acquiring the shared memory

Creating the message

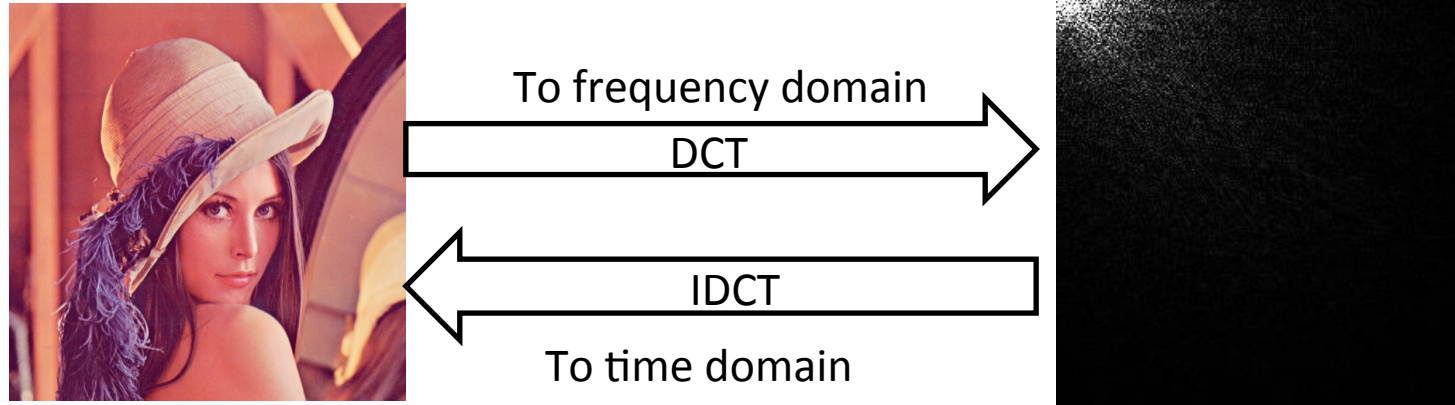
Writing the message to the shared memory.

DEMONSTRATION (HELLO WORLD)

OpenCL on Epiphany

- Browndeer COPRTHR SDK supports OpenCL on both ARM and Epiphany
- To use ARM, specify `CL_DEVICE_TYPE_CPU`
- To use Epiphany, specify `CL_DEVICE_TYPE_ACCELERATOR`

Application example (2D DCT)



DCT

$$F(i,j) = c(i)c(j) \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x,y) \cos[(2x+1)i\pi/2M] \cos[(2y+1)j\pi/2N]$$

We can parallelize with respect to i and j .

IDCT

$$f(x,y) = 4/MN \sum_{i=0}^{M-1} \sum_{j=0}^{N-1} c(i)c(j) F(i,j) \cos[(2x+1)i\pi/2M] \cos[(2y+1)j\pi/2N]$$

We can parallelize with respect to x and y .

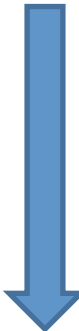
Program on Epiphany(DCT OpenCL)

```

__kernel void dct2d_kern(
    uint w,
    uint h,
    __global float* F,
    __global float* f)
{
    int i = get_global_id(0);
    int j = get_global_id(1);
    int x, y;
    float ci, cj;
    
$$F(i, j) = c(i)c(j) \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x, y) \cos[(2x+1)i\pi/2M] \cos[(2y+1)j\pi/2N]$$


    F[i*h+j] = 0;
    ci = i==0 ? 1/sqrt(2.0f) : 1.0f;
    cj = j==0 ? 1/sqrt(2.0f) : 1.0f;
    for(x=0; x<w; x++){
        for(y=0; y<h; y++){
            F[i*h+j] +=
                f[x*h+y] * (cos(((2.0f*x+1)*i*M_PI)/(2.0f*w))*cos(((2.0f*y+1)*j*M_PI)/(2.0f*h)));
        }
    }
    F[i*h+j] = ci*cj*F[i*h+j];
}

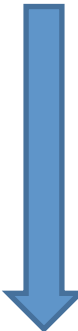
```



Program on Epiphany(IDCT OpenCL)

```
__kernel void idct2d_kern(
    uint w,
    uint h,
    __global float* F,
    __global float* f)
{
    int i = get_global_id(0);
    int j = get_global_id(1);
    int x, y;
    float ci, cj;
    
$$f(x,y) = 4/MN \sum_{i=0}^{M-1} \sum_{j=0}^{N-1} c(i)c(j)F(i,j)\cos[(2x+1)i\pi/2M]$$


    F[i*h+j] = 0;
    ci = i==0 ? 1/sqrt(2.0f) : 1.0f;
    cj = j==0 ? 1/sqrt(2.0f) : 1.0f;
    for(x=0;x<w; x++){
        for(y=0;y<h; y++){
            F[i*h+j] +=
                f[x*h+y] * (cos(((2.0f*x+1.0f)*i*M_PI)/(2.0f*w))*cos(((2.0f*y+1.0f)*j*M_PI)/(2.0f*h)));
        }
    }
    F[i*h+j] = ci*cj*F[i*h+j];
}
```



Program on Host

```
int main(int argc, char **argv)
{
    clGetPlatformIDs( 0,0,&nplatforms);
    platforms = (cl_platform_id*)malloc(nplatforms*sizeof(cl_platform_id));
    clGetPlatformIDs( nplatforms, platforms, 0);

    cl_context ctx = clCreateContext(ctxprop,1,&dev,0,0,&err);

    cl_command_queue cmdq = clCreateCommandQueue(ctx,dev,0,&err);

    cl_mem F_buf = clCreateBuffer(ctx,CL_MEM_USE_HOST_PTR,
        sizeof(float)*IMAGE_WIDTH*IMAGE_HEIGHT,F,&err);
    cl_mem f_buf = clCreateBuffer(ctx,CL_MEM_USE_HOST_PTR,
        sizeof(float)*IMAGE_WIDTH*IMAGE_HEIGHT,f,&err);

    cl_program prg = clCreateProgramWithSource(ctx,1,(const char**)&src,
        &src_sz,&err);
    clBuildProgram(prg,1,&dev,0,0,0);
    cl_kernel krn = clCreateKernel(prg,"dct2d_kern",&err);
```

Getting platform ID

Creating content

Create command queue

Allocating buffers

Compiling OpenCL program

Program on Host

```
clSetKernelArg(krn,0,sizeof(cl_uint),&IMAGE_WIDTH);
clSetKernelArg(krn,1,sizeof(cl_uint),&IMAGE_HEIGHT);
clSetKernelArg(krn,2,sizeof(cl_mem),&F_buf);
clSetKernelArg(krn,3,sizeof(cl_mem),&f_buf);

clEnqueueWriteBuffer(cmdq,f_buf,CL_TRUE,0,
    sizeof(float)*IMAGE_WIDTH*IMAGE_HEIGHT,f,0,0,0);
clEnqueueNDRangeKernel(cmdq,krn,2,0,gtdsz,ltdsz,0,0,&ev[0]);
clEnqueueReadBuffer(cmdq,F_buf,CL_TRUE,0,
    sizeof(float)*IMAGE_WIDTH*IMAGE_HEIGHT,F,0,0,&ev[1]);

err = clWaitForEvents(2,ev);
}
```

The diagram consists of five annotations with arrows pointing to specific lines of code in the OpenCL program:

- Mapping arguments**: Points to the four `clSetKernelArg` lines.
- Sending initial data**: Points to the `clEnqueueWriteBuffer` line.
- Queueing OpenCL program**: Points to the `clEnqueueNDRangeKernel` line.
- Reading the result**: Points to the `clEnqueueReadBuffer` line.
- Waiting program execution**: Points to the `clWaitForEvents` line.

DEMONSTRATION (OPENCL ON EPIPHANY)

Summary

- Epiphany is a manycore accelerator with 2D mesh network.
- Epiphany is controlled by the ARM core on Parallella.
- Supported programming tools
 - Hardwired programming SDK (ESDK)
 - Browndeer OpenCL